

SIMPLIFIED DELIVERY, ENHANCED COMMUNICATION

AGILE AND ROBUST FLUID AND SECURE NAVIGATION EFFECTIVE MARKETING TOOL ATTRACTIVE AND INTERACTIVE DESIGN

CHEF'S SPECIAL

KEENON

NERBOT T

Optimise your Service: Optimal Delivery and Impactful Communication



Agile and Robust

With its spacious trays and ultrastable chassis, the T10 combines agility and robustness. Designed to navigate with precision, it can move effortlessly through narrow passages of just 59 cm.



Fluid and Secure Navigation

Thanks to an advanced perception system, including stereo vision sensors, the T10 offers 3D detection covering 300°. This technology significantly enhances safety and ensures smooth, precise navigation, even in complex environments.



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Effective Marketing Tool

Equipped with a large advertising screen, the T10 displays customised images and videos to deliver your messages effectively and with impact.



Attractive and Interactive Design

Featuring a moving head, unique facial expressions and a design that integrates voice, touch and vision, the T10 offers captivating interactivity and contemporary elegance.

Weight

58 kg (128 lbs)

Jusqu'à 8 heures

Trays 1/2/3:

Lower tray:

11,6" (1920 x 1080)

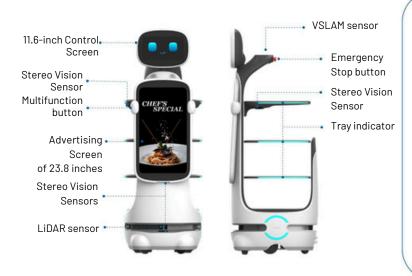
Tray size (default)

Autonomy of the battery*

48,6 x 41,6 cm (19,13" x 16,38")

35,0 x 28,6 cm (13,78" x 11,26")

Touch screen size (head)



Product specifications Dimensions

48,6 x 55,5 x 139,9 cm (19,13" x 21,85" x 54,69")

Maximum travel speed 1 m/s (3,28 ft/s)

Charging time** 5,5 hours

Total load capacity 40 kg (88 lbs)

Minimum passage width 59,0 cm (23,23")

* All indications concerning the battery depend on many factors; actual results may vary. The battery has a limited number of recharge cycles and may eventually need to be replaced. Battery life and charge cycles vary according to use and settings. ** The charging time indicated corresponds to the time required to charge from 15% to 100% of the battery's capacity, using either a charger or a charging point, with the robot switched on. Do not attempt to charge a wet robot.



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